Rack and Pinion System





How to Read Specifications Table

Specifications

Frame Size			60 mm	80 mm	
Actuator Product Name	Standard		LM2 500AZAC-	LM4 500AZAC-	
Actuator Product Name	with Electromagnetic Brake		LM2 500AZMC-	LM4 500AZMC-	
	Built-in Controller Type		AZD-AD (Single-Phase 100-120 VAC), AZD-CD (Single-Phase/Three-Phase 200-240 VAC)		
Driver Product Name	Pulse Input Type with RS-485	Pulse Input Type with RS-485 Communication		AZD-AX (Single-Phase 100-120 VAC), AZD-CX (Single-Phase/Three-Phase 200-240 VAC)	
	Pulse Input Type		AZD-A (Single-Phase 100-120 VAC), AZD-C (Single-Phase/Three-Phase 200-240 VAC)		
Equipped Motor (AZ Series)			AZ	LW66	
Maximum Speed		mm/s		500	
Transportable Mass		kg	10 (250 mm/s) 7 (500 mm/s)	20(250 mm/s) 7(500 mm/s)	
Maximum Acceleration		m/s ²		1	
Thrust*1		N	110 (250 mm/s) 77 (500 mm/s)	220 (250 mm/s) 77 (500 mm/s)	
Push Force		N	110	220	
Lalding Fores	Power On	N	110	220	
Holding Force	with Electromagnetic Brake	N	110	220	
Minimum Travel Amount		mm		0.01	
Rotor Inertia		J:kg · m ²		0×10 ⁻⁷ ×10 ⁻⁷)*2	
- Stroke		mm	100, 200, 300, 400, 500, 600, 700, or 800	100, 200, 300, 400, 500, 600, 700, 800, 900, or 1000	
Power Supply Input	Voltage and Frequency		Single-Phase/Thre	e 100-120 VAC, e-Phase 200-240 VAC 6% 50/60Hz	
	Input Current	Single-Phase 100-120 VAC		3.8	
	A	Single-Phase 200-240 VAC		2.3	
		Three-Phase 200-240 VAC		1.4	
Control Power Supply			24 VDC+5%*3	0.25 A (0.5A)*2	

Depending on the product, limitations and caution may be required for usage. For details, refer to the notes on each product page.

①Maximum Speed

The maximum speed allowed when transporting the transportable mass.

②Transportable Mass

Mass that can be moved under operating performance of the rack and pinion motor.

③Maximum Acceleration

The maximum acceleration allowed when the transportable mass is transferred.

④Thrust

The force that the rack can push the load during constant speed operation.

⑤Push Force

The pressure applied to the load at push-motion operation.

6 Holding Force

Holding force when the motor is stopped or when the electromagnetic brake is operating, while power is supplied.

Minimum Travel Amount

The minimum distant that the rack travels. (Factory setting)

(8) Rotor Inertia

This refers to the inertia of the rotor inside the equipped motor.

Stroke

The maximum distance the rack can be pushed and pulled.

Rack and Pinion System \mathcal{A}_{STEP} AZSeries Equipped AC Power Supply Input

For technical references, regulations, and standards related to these products, please see the Oriental Motor website.

Product Number

	ack and Pinion Mot	ors AZMC-1
1) 234	5 6 7 8
1	Series Name	LM: L Series Rack and Pinion Motor
2	Frame Size	2: 60 mm 4: 80 mm
3	Moving Direction of Rack	F: Vertical to Mounting Foot Surface B: Horizontal to Mounting Foot Surface
4	Rack Maximum Speed	40 : 40 mm/s 90 : 90 mm/s 500 : 500 mm/s
(5)	Equipped Motor	AZ: AZ Series
6	Motor Type	A: Standard M: with Electromagnetic Brake
\bigcirc	Motor Power Supply Input	C: AC Power Supply Input Specifications
8	Stroke	1: 100 mm 2: 200 mm 3: 300 mm 4: 400 mm 5: 500 mm 6: 600 mm 7: 700 mm 8: 800 mm 9: 900 mm 10: 1000 mm

$\frac{\textbf{AZD}}{1} - \frac{\textbf{C}}{2} \frac{\textbf{D}}{3}$

1	Driver Type	AZD: AZ Series Driver
2	Power Supply Input	A: Single-Phase 100-120 VAC C: Single-Phase/Three-Phase 200-240 VAC
3	Туре	D: Built-in Controller Type X: Pulse Input Type with RS-485 Communication Blank: Pulse Input Type

Connection Cable Sets/Flexible Connection Cable Sets

$\frac{\mathbf{CC}}{1} \frac{\mathbf{050}}{2} \frac{\mathbf{V}}{3} \frac{\mathbf{Z}}{4} \frac{\mathbf{F}}{5} \frac{\mathbf{B}}{6}$

1		CC: Cable
2	Length	005 :0.5 m 010 :1 m 015 :1.5 m 020 :2 m 025 :2.5 m 030 :3 m 040 :4 m 050 :5 m
		070 : 7 m 100 : 10 m 150 : 15 m 200 : 20 m
3	Reference Number	
4	Applicable Model	Z: AZ Series
5	Cable Type	F: Connection Cable Set R: Flexible Connection Cable Set
6	Electromagnetic Brake	Blank: without Electromagnetic Brake B: with Electromagnetic Brake

Product Line

Rack and Pinion Motors
High-Speed Type



Frame Size	Product Name	List Price
	LM20500AZAC-1	
	LM2 500AZAC-2	
	LM2 500AZAC-3	
<u> </u>	LM2 500AZAC-4	
60 mm	LM2 500AZAC-5	
	LM2_500AZAC-6	
	LM2 500AZAC-7	
	LM2_500AZAC-8	
	LM4 500AZAC-1	
	LM4 500AZAC-2	
	LM4 500AZAC-3	
	LM4 500AZAC-4	
00	LM4 500AZAC-5	
80 mm	LM4 500AZAC-6	
	LM4 500AZAC-7	
	LM4 500AZAC-8	
	LM4_500AZAC-9	
	LM4 500AZAC-10	

◇Large Transportable Mass Type



Frame Size	Product Name	List Price
	LM2 90AZAC-1	
	LM2 90AZAC-2	
	LM2 90AZAC-3	
00	LM2 90AZAC-4	
60 mm	LM2 90AZAC-5	
	LM2 90AZAC-6	
	LM2 90AZAC-7	
	LM2 90AZAC-8	
	LM4 40AZAC-1	
	LM4 40AZAC-2	
	LM4 40AZAC-3	
	LM4 40AZAC-4	
00	LM4 40AZAC-5	
80 mm	LM4 40AZAC-6	
	LM4 40AZAC-7	
	LM4 40AZAC-8	
	LM4 40AZAC-9	
	LM4 40AZAC-10	

◇High-Speed Type with Electromagnetic Brake



Frame Size	Product Name	List Price
	LM2_500AZMC-1	
	LM2 500AZMC-2	
	LM2_500AZMC-3	
60 mm	LM2 500AZMC-4	
60 11111	LM2 500AZMC-5	
	LM2 500AZMC-6	
	LM2 500AZMC-7	
	LM2 500AZMC-8	
	LM4 500AZMC-1	
	LM4 500AZMC-2	
	LM4 500AZMC-3	
	LM4 500AZMC-4	
80 mm	LM4 500AZMC-5	
00 11111	LM4_500AZMC-6	
	LM4 500AZMC-7	
	LM4 500AZMC-8	
	LM4 500AZMC-9	
	LM4 500 AZMC-10	

◇Large Transportable Mass Type with Electromagnetic Brake



with Elect	tromagnetic Brake	
Frame Size	Product Name	List Price
	LM2 90AZMC-1	
	LM2 90AZMC-2	
	LM2 90AZMC-3	
	LM2 90AZMC-4	
60 mm	LM2 90AZMC-5	
	LM2 90AZMC-6	
	LM2 90AZMC-7	
	LM2 90AZMC-8	
	LM4 40AZMC-1	
	LM4 40AZMC-2	
	LM4 40AZMC-3	
	LM4 40AZMC-4	
00	LM4 40AZMC-5	
80 mm	LM4 40AZMC-6	
	LM4 40AZMC-7	
	LM4 40AZMC-8	
	LM4 40AZMC-9	
	LM4 40AZMC-10	

Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box
 is located within the product name.

 Drivers Built-in Controller Type 		-
Power Supply Input	Product Name	List Price
Single-Phase 100-120 VAC	AZD-AD	
Single-Phase/Three-Phase 200-240 VAC	AZD-CD	
◇Pulse Input Type		I
Power Supply Input	Product Name	List Price
Single-Phase 100-120 VAC	AZD-A	
Single-Phase/Three-Phase 200-240 VAC	AZD-C	

Single-Phase/Inree-Phase 200-240 VAC AZD-C

Connection Cable Sets/Flexible Connection Cable Sets

Use the flexible connection cable in application where the cable is bent and flexed.

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting toa driver, use a connection cable.

◇For Motors/Encoders

		$\mathbf{i} \in \mathbf{i}$	\supset
	For Moto	rs For	Encoders
Product Line	Length L (m)	Product Name	List Price
	0.5	CC005VZF	
	1	CC010VZF	
	1.5	CC015VZF	
	2	CC020VZF	
	2.5	CC025VZF	
Connection Cable Sets	3	CC030VZF	
Connection Cable Sets	4	CC040VZF	
	5	CC050VZF	
	7	CC070VZF	
	10	CC100VZF	
	15	CC150VZF	
	20	CC200VZF	
	0.5	CC005VZR	
	1	CC010VZR	
	1.5	CC015VZR	
	2	CC020VZR	
	2.5	CC025VZR	
	3	CC030VZR	
Flexible Connection Cable Sets	4	CC040VZR	
	5	CC050VZR	
	7	CC070VZR	
	10	CC100VZR	
	15	CC150VZR	
	20	CC200VZR	

$\bigcirc {\sf For}$ Motors/Encoders/Electromagnetic Brakes

	\bigcirc		
For Motors	For Encoders	For Electromagnetic	Brakes
Product Line	Length L (m)	Product Name	List Price
	0.5	CC005VZFB	
	1	CC010VZFB	
	1.5	CC015VZFB	
	2	CC020VZFB	
	2.5	CC025VZFB	
Organization Oakla Cata	3	CC030VZFB	
Connection Cable Sets	4	CC040VZFB	
	5	CC050VZFB	
	7	CC070VZFB	
	10	CC100VZFB	
	15	CC150VZFB	
	20	CC200VZFB	
	0.5	CC005VZRB	
	1	CC010VZRB	
	1.5	CC015VZRB	
	2	CC020VZRB	
	2.5	CC025VZRB	
	3	CC030VZRB	
Flexible Connection Cable Sets	4	CC040VZRB	
	5	CC050VZRB	
	7	CC070VZRB	
	10	CC100VZRB	
	15	CC150VZRB	
	20	CC200VZRB	

Included

Rack and Pinion Motors

Туре	Included	Operating Manual
Common to All Types		1 Сору
Drivers		

Billiolo		
Type	Connector	Operating Manual
Common to All Types	CN1 Connector (1 pc.) CN4 Connector (1 pc.) CN5 Connector (1 pc.) Connector Lever (1 pc.)	1 Сору

Connection Cable Sets/Flexible Connection Cable Sets

Type	Operating Manual
Connection Cable Set	-
Flexible Connection Cable Set	1 Сору



\bigcirc Pulse Input Type with RS-485 Communication

Power Supply Input	Product Name	List Price
Single-Phase 100-120 VAC	AZD-AX	
Single-Phase/Three-Phase 200-240 VAC	AZD-CX	

System Configuration

Combination of L Series with Electromagnetic Brake and either Built-in Controller Type Driver or Pulse Input Type Driver with RS-485 Communication

This is an example of a configuration using I/O control or RS-485 communication in a built-in controller type driver.

Rack and pinion motors, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.



The system configuration shown above is an example. Other combinations are also available.

Note:

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

Combination of L Series with Electromagnetic Brake and Pulse Input Type Driver This is an example of a single-axis system configuration using a programmable controller (with pulse generating function). Rack and pinion motors, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.



The system configuration shown above is an example. Other combinations are also available.
Natural

Note:

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

High-Speed Type

Specifications

Frame Size			60 mm	80 mm	
Actuator Product Name	Standard		LM2 500AZAC-	LM4 500AZAC-	
ACTUATOR PRODUCT NAME	with Electromagnetic Brake		LM2_500AZMC-	LM4_500AZMC-	
	Built-in Controller Type		AZD-AD (Single-Pha AZD-CD (Single-Phase/Thr		
Driver Product Name	Pulse Input Type with RS-485 Co	ommunication	AZD-AX (Single-Pha AZD-CX (Single-Phase/Thr		
	Pulse Input Type		AZD-A (Single-Phase 100-120 VAC), AZD-C (Single-Phase/Three-Phase 200-240 VAC)		
Equipped Motor (AZ Series)	I		AZM6	6	
Maximum Speed		mm/s	500		
Transportable Mass		kg	10 (250 mm/s) 7 (500 mm/s)	20(250 mm/s) 7(500 mm/s)	
Maximum Acceleration		m/s ²	1		
Thrust*1	rust*1 N		110 (250 mm/s) 77 (500 mm/s)	220(250 mm/s) 77(500 mm/s)	
Push Force		N	110	220	
Under a France	Power On	N	110	220	
Holding Force	with Electromagnetic Brake	Ν	110	220	
/linimum Travel Amount		mm	0.01		
Rotor Inertia		J:kg · m ²	370×10 (530×10 ⁻		
Stroke		mm	100, 200, 300, 400, 500, 600, 700, or 800	100, 200, 300, 400, 500, 600, 700, 800, 900, or 1000	
	Voltage and Frequency		Single-Phase 100-120 VAC, Single-Phase/Three-Phase 200-240 VAC -15 to +6% 50/60Hz		
Power Supply Input	Input Current	Single-Phase 100-120 VAC	3.8		
	A	Single-Phase 200-240 VAC	2.3		
		Three-Phase 200-240 VAC	1.4		
Control Power Supply			24 VDC±5%*3 0.2	25 A (0.5A)*2	

● Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box □ is located within the product name. A number indicating the rack stroke is entered where the box □ is located within the product name.

When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack mass. *1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

*2 The bracket () indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

Positioning Distance - Positioning Time

Check the positioning time (reference) from the positioning distance. The positioning time differs depending on the transportable mass. **LM2**



LM4



Repetitive Positioning Accuracy (Reference Value)

It is the value measured with the transportable mass. It varies depending on load, driving condition or mounting direction.

	Product Name	Rack Moving Direction	Repetitive Positioning Accuracy [mm]		
	LM2 Horizontal LM4 Direction		+0.25		
			±0.25		
	LM2 Vertical		0.07		
	LM4	Direction	±0.07		

Operating Speed - Transportable Mass



Note:

The operating speed - transportable mass characteristics shows the data based on Oriental Motor's measurement conditions. The characteristics may change depending on the conditions of the power supply voltage and the ambient temperature.

Depending on the driving conditions, a considerable amount of heat may be generated by the motor. To protect the absolute sensor, be sure to keep the temperature of the motor case at 80°C or less. (When conforming to the UL/CSA Standards, it is required to keep the temperature of the motor case at 75°C or less since the motor is recognized as resistant class A.)

Large Transportable Mass Type

Specifications

Frame Size			60 mm	80 mm		
Astronom Desident Names	Standard		LM2 90AZAC-	LM4 40AZAC-		
Actuator Product Name	with Electromagnetic Brake		LM2_90AZMC	LM4_40AZMC-		
	Built-in Controller Type		AZD-AD (Single-Phase 100-120 VAC), AZD-CD (Single-Phase/Three-Phase 200-240 VAC)			
Driver Product Name	Pulse Input Type with RS-485 Com	munication		Phase 100-120 VAC), Three-Phase 200-240 VAC)		
	Pulse Input Type		AZD-A (Single-Phase 100-120 VAC), AZD-C (Single-Phase/Three-Phase 200-240 VAC)			
Equipped Motor (AZ Series)			AZ	M66		
Maximum Speed		mm/s	90	40		
Transportable Mass		kg	30	100 (20 mm/s) 70 (40 mm/s)		
Maximum Acceleration		m/s ²	0.187	0.074		
Thrust ^{*1}		Ν	306	1008(20 mm/s) 705(40 mm/s)		
Push Force		N	306	1008		
Holding Force	Power On	N	306	1008		
noiulity force	with Electromagnetic Brake	N	306 1008			
Minimum Travel Amount		mm	0.001			
Rotor Inertia		J:kg · m ²		×10 ⁻⁷ 10 ⁻⁷)*2		
Stroke		mm	100, 200, 300, 400, 500, 600, 700, or 800	100, 200, 300, 400, 500, 600, 700, 800, 900, 1000		
	Voltage and Frequency		Single-Phase 100-120 VAC, Single-Phase/Three-Phase 200-24 -15 to +6% 50/60Hz			
Power Supply Input	Input Current	Single-Phase 100-120 VAC	3.8			
	A	Single-Phase 200-240 VAC	2.3			
		Three-Phase 200-240 VAC		.4		
Control Power Supply			24 VDC±5% ^{*3}	0.25 A (0.5 A)*2		

Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box is located within the product name. A number indicating the rack stroke is entered where the box is located within the product name.

When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack mass. *1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

*2 The bracket () indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

Positioning Distance - Positioning Time

Check the positioning time (reference) from the positioning distance. The positioning time differs depending on the transportable mass. ${\bf LM2}$





Repetitive Positioning Accuracy (Reference Value)

It is the value measured with the transportable mass. It varies depending on load, driving condition or mounting direction.

Product Name	Rack Moving Direction	Repetitive Positioning Accuracy [mm]		
LM2 Horizontal		±0.25		
LM4 Direction				
LM2 Vertical		+0.07		
LM4 Direction		±0.07		

Operating Speed - Transportable Mass



Note:

The operating speed - transportable mass characteristics shows the data based on Oriental Motor's measurement conditions. The characteristics may change depending on the conditions of the power supply voltage and the ambient temperature.

Depending on the driving conditions, a considerable amount of heat may be generated by the motor. To protect the absolute sensor, be sure to keep the temperature of the motor case at 80°C or less. (When conforming to the UL/CSA Standards, it is required to keep the temperature of the motor case at 75°C or less since the motor is recognized as resistant class A.)

Electromagnetic Brake Specifications

Product Name		LM2	LM4	
Brake Type		Power Off Activated Type		
Power Supply Voltage		24 ∨ DC±5%*		
Power Supply Current	Α	0.25		
Brake Operating Time	ms	20		
Brake Releasing Time	ms	30		
Time Rating		Continuous		

*For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

General Specifications



			Driver			
		Rack and Pinion Motor	Built-in Controller Type Pulse Input Type with RS-485 Communication	Pulse Input Type		
Thermal Class		130 (B) [UL/CSA Recognized 105 (A)]	-			
Insulation Resis	stance	100 MΩ or more when a 500 VDC megger is applied between the following places: · Case – Motor Windings · Case – Electromagnetic Brake Windings*2	100 MΩ or more when a 500 VDC megger is applied between the following places: • Protective Earth Terminal – Power Supply Terminal • Encoder Connector – Power Supply Terminal • I/O Signal Terminal – Power Supply Terminal			
Dielectric Stren	gth	Sufficient to withstand the following for 1 minute: · Case – Motor Windings 1.5 kVAC, 50 Hz or 60 Hz · Case – Electromagnetic Brake Windings ^{*2} 1.5 kVAC, 50 Hz or 60 Hz	z • Protective Earth Terminal – Power Supply Terminal 1.5 kVAC, 50Hz or 60I			
Operating	Ambient Temperature	0 to +40°C (Non-freezing)*3 0 to +55°C (Non-freezing)*4				
Environment	Ambient Humidity	85%	or less (Non-condensing)			
	Atmosphere	No corrosive gases or dust. The product should not be exposed to water or oil.				
Degree of Protection IP30 (Excluding rack moving part and connector part)			IP10 IP20			
Multiple Rotation Detection Range in Power OFF State (Motor Output Shaft)		±900	Rotations (1800 Rotations)			

*1 The motor product name (not the actuator product name) is recognized by UL under the UL and Canada Standards.

The motor product name (not the actuator product name) conforms to the standards to affix the CE Marking. *2 Only for products with an electromagnetic brake.

*3 It is based on Oriental Motor's measurement conditions.

*4 When installing a motor to a heat sink of a capacity at least equivalent to an aluminum plate of 200×200 mm, thickness 2 mm.

Note:

Disconnect the motor and driver when taking an insulation resistance measurement or performing a dielectric voltage withstand test. Also, do not perform these tests on the absolute sensor part of the motor.

Moving Direction

At the time of shipment, the moving direction of the rack is set as shown below.

В Туре



Rack Permissible Rotational Torque (Moment)

Product Name	Rack Permissible Rotational Torque (Moment)				
LM2	0.3 N·m max.				
LM4	0.5 N·m max.				
	0.5 N III IIIax.				

Keep the rotational torque below the permissible value.

If the rotational torque is applied too much, the rack bushing will wear in a short time.



Permissible Radial Load

Permissible Radial Load Unit: N							
Stroke mm	LM2_90	LM2_500	LM4□40	LM4□500			
100	25	25*1	120	60*1			
200	20	20*1	90	40*1			
300	10	10*1	70	30*1			
400	10	10*1	60	25 ^{*1}			
500	7	7*1	50	20*1			
600	*2	*2	40	15 ^{*1}			
700	*2	*2	40	10*1			
800	*2	*2	25	7*1			
900	-	-	20	*2			
1000	-	-	15	*2			

● Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box □ is located within the product name.

1 The value is the operation speed up to 90 mm/s. When operating at a speed exceeding 90 mm/s, do not apply a radial load to the rack by providing a guide, etc..
 2 Do not apply a radial load to the rack by providing a guide, etc. since the rack is damaged.



Rack and Pinion System \mathcal{A}_{STEP} AZSeries Equipped DC Power Supply Input

For technical references, regulations, and standards related to these products, please see the Oriental Motor website.

Product Number

Rack and Pinion Motors

L	Μ	4	F	150	AZ	Μ	Κ	-	1	
(D	2	3	4	5	6	7		8	
1	Series N	lame		LM : L	Series Rack ar	nd Pinion Mo	otor			
2	Frame S	Size		2 : 60 4 : 80						
3	Moving Direction of Rack F: Vertical to Mounting Foot Surface B: Horizontal to Mounting Foot Surface									
4	Rack Ma	aximum Sp	eed	20 : 2	0 mm/s 50	: 50 mm/s	150 : 1	50 mm/s	200	: 200 mm/s
5	Equippe	d Motor		AZ : A	Z Series					
6	Motor Type A: Standard M: with Electromagnetic Brake									
0	Motor Power Supply Input K : DC Power Supply Input Specifications									
8	Stroke				0 mm 2 ∶ 20 0 mm 6 ∶ 60				0 mm	

Drivers

AZD - K D

	1 2	3
1	Driver Type	AZD : AZ Series Driver
2	Power Supply Input	K : 24/48 VDC
3	Туре	 D : Built-in Controller Type X : Pulse Input Type with RS-485 Communication Blank : Pulse Input Type

Connection Cable Sets/Flexible Connection Cable Sets

С	С	050	V	Ζ	F	Β	2	
(D	2	3	4	5	6	7	
1				CC : Ca	able			
2	Length	I		025	: 2.5 m	030	:3 m	015 : 1.5 m 020 : 2 m 040 : 4 m 050 : 5 m 150 : 15 m 200 : 20 m
3	Refere	nce Number						
4	Applica	able Model		ZIA	Z Serie	es		
5	Cable ⁻	Гуре		F: Connection Cable Set R: Flexible Connection Cable Set				
6	Electro	magnetic Brake		Blank: without Electromagnetic Brake B: with Electromagnetic Brake				
0	Power	Supply Cable		2 : DC	Power S	upply Inp	out	

Product Line

Rack and Pinion Motors ◇High-Speed Type



Frame Size	Product Name	List Price
	LM2200AZAK-1	
	LM2200AZAK-2	
60 mm	LM2200AZAK-3	
	LM2200AZAK-4	
	LM2200AZAK-5	
	LM40150AZAK-1	
	LM40150AZAK-2	
	LM40150AZAK-3	
80 mm	LM40150AZAK-4	
	LM40150AZAK-5	
	LM40150AZAK-6	
	LM40150AZAK-10	

○High-Speed ⁻ Electromagne	21 A	
Frame Size	Product Name	List Price
	LM2200AZMK-1	
	LM22200AZMK-2	
60 mm	LM2 200AZMK-3	
	LM22200AZMK-4	
	LM2200AZMK-5	
	LM4D150AZMK-1	
	LM4D150AZMK-2	
	LM4D150AZMK-3	
80 mm	LM4D150AZMK-4	
	LM4D150AZMK-5	
	LM4D150AZMK-6	
	LM40150AZMK-10	



◇Large Transportable Mass Type

Frame Size	Product Name	List Price
	LM2D50AZAK-1	
	LM2D50AZAK-2	
60 mm	LM2D50AZAK-3	
	LM2 50AZAK-4	
	LM2_50AZAK-5	
	LM420AZAK-1	
	LM420AZAK-2	
	LM420AZAK-3	
80 mm	LM420AZAK-4	
	LM420AZAK-5	
	LM420AZAK-6	
	LM420AZAK-10	

◇Large Transportable Mass Type with Electromagnetic Brake					
Frame Size	Product Name	List Price			
60 mm	LM2_50AZMK-1 LM2_50AZMK-2 LM2_50AZMK-3 LM2_50AZMK-4 LM2_50AZMK-5				
80 mm	LM4 20AZMK-1 LM4 20AZMK-2 LM4 20AZMK-3 LM4 20AZMK-4 LM4 20AZMK-5 LM4 20AZMK-6 LM4 20AZMK-6				

Either F (vertical to the mounting foot surface) or B (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box is located within the product name. Note: LM4 20AZAK-10 and LM4 20AZMK-10 cannot be used in combination with the Multi-Axis Driver SSCNET III /H Compatible.

Drivers Øuilt-in Controller Type				\Diamond Pulse Input Type wi	ith RS-485 Comm	unication
Power Supply Input	Product Name	List Price		Power Supply Input	Product Name	List Pric
24/48 VDC	AZD-KD	Liot 1 100		24/48 VDC	AZD-KX	
OPulse Input Type			T			
Power Supply Input	Product Name	List Price				
24/48 VDC	AZD-K					

Connection Cable Sets/Flexible Connection Cable Sets

Use the flexible connection cable in application where the cable is bent and flexed. The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

◇For Motors/Encoders

	ø	$\langle \rangle$	
		\searrow	
		For Motors	For Encoders
Product Line	Length (m)	Product Name	List Price
	0.5	CC005VZF2	
	1	CC010VZF2	
	1.5	CC015VZF2	
	2	CC020VZF2	
	2.5	CC025VZF2	
Connection	3	CC030VZF2	
Cable Sets	4	CC040VZF2	
	5	CC050VZF2	
	7	CC070VZF2	
	10	CC100VZF2	
	15	CC150VZF2	
	20	CC200VZF2	
	0.5	CC005VZR2	
	1	CC010VZR2	
	1.5	CC015VZR2	
	2	CC020VZR2	
	2.5	CC025VZR2	
Flexible Connection	3	CC030VZR2	
Cable Sets	4	CC040VZR2	
Cable Sets	5	CC050VZR2	
	7	CC070VZR2	
	10	CC100VZR2	
	15	CC150VZR2	
	20	CC200VZR2	

\bigcirc For Motors/Encoders/Electromagnetic Brakes





List Price

For Motors	For Encod	lers For Elect	For Electromagnetic Brakes	
Product Line	Length (m)	Product Name	List Price	
	0.5	CC005VZFB2		
	1	CC010VZFB2		
	1.5	CC015VZFB2		
	2	CC020VZFB2		
	2.5	CC025VZFB2		
Connection	3	CC030VZFB2		
Cable Sets	4	CC040VZFB2		
	5	CC050VZFB2		
	7	CC070VZFB2		
	10	CC100VZFB2		
	15	CC150VZFB2		
	20	CC200VZFB2		
	0.5	CC005VZRB2		
	1	CC010VZRB2		
	1.5	CC015VZRB2		
	2	CC020VZRB2		
	2.5	CC025VZRB2		
Flexible Connection	3	CC030VZRB2		
Cable Sets	4	CC040VZRB2		
Cable Sets	5	CC050VZRB2		
	7	CC070VZRB2		
	10	CC100VZRB2		
	15	CC150VZRB2		
	20	CC200VZRB2		

Included

Rack and Pinion Motors

Туре	Included	Operating Manual
Common to All Ty	Des	1 Сору
Drivers		

Type	Connector	Operating Manual
Common to All Types	· CN1 Connector (1 pc.) · CN4 Connector (1 pc.)	1 Сору

Connection Cable Sets/Flexible Connection Cable Sets

Type	Operating Manual
Connection Cable Set	-
Flexible Connection Cable Set	1 Сору

System Configuration

Combination of L Series with Electromagnetic Brake and either Built-in Controller Type Driver or Pulse Input Type Driver with RS-485 Communication

This is an example of a configuration using I/O control or RS-485 communication in a built-in controller type driver.

Rack and pinion motors, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.



The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

Combination of L Series with Electromagnetic Brake and Pulse Input Type Driver This is an example of a single-axis system configuration using a programmable controller (with pulse generating function). Rack and pinion motors, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.

Purchase is required

OPurchase as necessary



The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

High-Speed Type

Specifications

Frame Size			60 mm	80 mm	
Actuator Product Name	Standard		LM2200AZAK-	LM4 150AZAK-	
Actuator Product Name	with Electromagnetic Brake		LM2200AZMK-	LM4 150AZMK-	
	Built-in Controller Type		AZ	D-KD	
Driver Product Name	Pulse Input Type with RS-485 Communi	ication	AZ	D-KX	
	Pulse Input Type		AZ	ZD-K	
Equipped Motor (AZ Series)			AZ	M66	
Maximum Cacad	24 VDC	mm/s	200	150	
Maximum Speed	48 VDC	mm/s	250	250	
	24 VDC	Kg	10(100 mm/s) 5(200 mm/s)	20 (60 mm/s) 7 (150 mm/s)	
Fransportable Mass	48 VDC	Kg	10 (250 mm/s)	20 (150 mm/s) 7 (250 mm/s)	
Maximum Acceleration		m/s ²		1	
¥1	24 VDC	N	110 (100 mm/s) 55 (200 mm/s)	220 (60 mm/s) 77 (150 mm/s)	
Fhrust ^{*1}	48 VDC	N	110 (250 mm/s)	220 (150 mm/s) 77 (250 mm/s)	
Push Force		N	110	220	
Juldian Farma	Power On	N	110	220	
lolding Force	with Electromagnetic Brake	N	110	220	
/linimum Travel Amount		mm).01	
Rotor Inertia		J:kg · m ²	370×10 ⁻⁷ (530×10 ⁻⁷)*2		
Stroke		mm	100, 200, 300, 400, 500	100, 200, 300, 400, 500, 600, 1000	
	Voltage		24 VDC ±5%	* ³ /48 VDC ±5%	
Power Supply Input	Input Current	A	3.55	(3.8)*2	

● Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box □ is located within the product name. A number indicating the rack stroke is entered where the box □ is located within the product name.

When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack mass. *1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

 $\mathbf{\ast2}$ The bracket ($\$) indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

Positioning Distance - Positioning Time

Check the positioning time (reference) from the positioning distance. The positioning time differs depending on the transportable mass.



Repetitive Positioning Accuracy (Reference Value)

It is the value measured with the transportable mass. It varies depending on load, driving condition or mounting direction.

Product Name	Rack Moving Direction	Repetitive Positioning Accuracy [mm]	
LM2	Horizontal	±0.25	
LM4 Direction		±0.25	
LM2	Vertical	±0.07	
LM4 Direction		±0.07	

Operating Speed - Transportable Mass



- - LM2□200 LM40150 200 250 300 Operating Speed [mm/s]

Note:

The operating speed - transportable mass characteristics shows the data based on Oriental Motor's measurement conditions. The characteristics may change depending on the conditions of the power supply voltage and the ambient temperature.

Depending on the driving conditions, a considerable amount of heat may be generated by the motor. To protect the absolute sensor, be sure to keep the temperature of the motor case at 80°C or less. (When conforming to the UL/CSA Standards, it is required to keep the temperature of the motor case at 75°C or less since the motor is recognized as resistant class A.)

Large Transportable Mass Type

Specifications

Frame Size			60 mm	80 mm	
Actuator Product Name	Standard		LM2 50AZAK-	LM4 20AZAK-	
ACTUATOR Product Name	with Electromagnetic Brake		LM2_50AZMK-	LM4 20AZMK-	
	Built-in Controller Type		AZ	D-KD	
Driver Product Name	Pulse Input Type with RS-485 Commun	nication	AZ	D-KX	
	Pulse Input Type		A	ZD-K	
Equipped Motor (AZ Series)			AZ	LM66	
Maximum Speed	24 VDC	mm/s	50	20	
Maximum Speed	48 VDC	mm/s	60	25	
Trananastabla Masa	24 VDC	Kg	30	100 (10 mm/s) 50 (20 mm/s)	
Fransportable Mass	48 VDC	Kg	30	100 (15 mm/s) 50 (25 mm/s)	
Maximum Acceleration		m/s ²	0.187	0.074	
ſhrust*1	24 VDC	N	306	1008 (10 mm/s) 504 (20 mm/s)	
Inrust	48 VDC	Ν	306	1008 (15mm/s) 504 (25mm/s)	
Push Force		N	306	1008	
Iniding Force	Power On	N	306	1008	
lolding Force	with Electromagnetic Brake	N	306	1008	
/linimum Travel Amount		mm	C	1.001	
Rotor Inertia		J:kg · m ²	370×10^{-7} (530×10^{-7})*2		
Stroke		mm	100, 200, 300, 400, 500	100, 200, 300, 400, 500, 600, 1000	
Denner Conseliu lanut	Voltage		24 VDC ±5%	*3/48 VDC ±5%	
Power Supply Input	Input Current	A	3.55	(3.8)*2	

● Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box □ is located within the product name. A number indicating the rack stroke is entered where the box □ is located within the product name.

When the rack is moved in the vertical direction, the load mass that can be driven is the value obtained by subtracting the rack mass from the transportable mass. Refer to 'Dimensions' for the rack mass. *1 For a value obtained by adding the acceleration thrust of a load to the load thrust, do not exceed the thrust amount.

*2 The bracket () indicates the value for the product with an electromagnetic brake.

*3 For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

Note:

LM4 20AZAK-10 and LM4 20AZMK-10 cannot be used in combination with the Multi-Axis Driver SSCNET II /H Compatible.

Positioning Distance - Positioning Time

Check the positioning time (reference) from the positioning distance. The positioning time differs depending on the transportable mass.







Repetitive Positioning Accuracy (Reference Value)

It is the value measured with the transportable mass. It varies depending on load, driving condition or mounting direction.

Product Name	Rack Moving Direction	Repetitive Positioning Accuracy [mm]		
LM2	Horizontal	10.05		
LM4	Direction	±0.25		
LM2	Vertical	0.07		
LM4	Direction	±0.07		

Operating Speed - Transportable Mass





Note:

The operating speed - transportable mass characteristics shows the data based on Oriental Motor's measurement conditions. The characteristics may change depending on the conditions of the power supply voltage and the ambient temperature.

Depending on the driving conditions, a considerable amount of heat may be generated by the motor. To protect the absolute sensor, be sure to keep the temperature of the motor case at 80°C or less. (When conforming to the UL/CSA Standards, it is required to keep the temperature of the motor case at 75°C or less since the motor is recognized as resistant class A.)

Electromagnetic Brake Specifications

Product Name		LM2	LM4		
Brake Type		Power Off Ac	tivated Type		
Power Supply Voltage		24 ∨ DC±5%*			
Power Supply Current	Α	0.25			
Brake Operating Time	ms	2	0		
Brake Releasing Time	ms	3	0		
Time Rating		Contir	nuous		

*For the type with an electromagnetic brake, a 24 VDC±4% specification applies if the wiring distance between the motor and the driver is extended to 20 m using a cable.

General Specifications



		Rack and Pinion Motor	Driver		
Thermal Class		130 (B) [UL/CSA Recognized 105 (A)]	_		
Insulation Resistance		100 MΩ or more when a 500 VDC megger is applied between the following places: · Case – Motor Windings · Case – Electromagnetic Brake Windings ^{*3}	100 $M\Omega$ or more when a 500 VDC megger is applied between the following places: \cdot Protective Earth Terminal – Power Supply Terminal		
Dielectric Strengt	Sufficient to withstand the following for 1 minute: ctric Strength Case – Motor Windings 1.0 kVAC 50Hz or 60Hz · Case – Electromagnetic Brake Windings*3 1.0 kVAC		_		
Operating	Ambient Temperature	0 to $+40^{\circ}$ C (Non-freezing)*4	0 to $+50^{\circ}$ C (Non-freezing)		
Environment	Ambient Humidity	85% or less (Non-	-condensing)		
	Atmosphere	No corrosive gases or dust. The product s	hould not be exposed to water or oil.		
Degree of Protect	tion	IP30 (Excluding rack moving part and connector part)	IP10		
Multiple Rotation Detection Range in Power OFF State (Motor Output Shaft)		±900 Rotations (1800 Rotations)			

***1** The motor product name (not the actuator product name) is recognized by UL under UL and Canada Standards.

The motor product name (not the actuator product name) conforms to the standards to affix the CE Marking.

*2 Only for the motor part.

*****3 Only for products with an electromagnetic brake.

*4 It is based on Oriental Motor's measurement conditions.

Note:

Disconnect the motor and driver when taking an insulation resistance measurement or performing a dielectric voltage withstand test. Also, do not perform these tests on the absolute sensor part of the motor.

Moving Direction

At the time of shipment, the moving direction of the rack is set as shown below.

B Type



Rack Permissible Rotational Torque (Moment)

Product Name	Rack Permissible Rotational Torque (Moment)
LM2	0.3 N·m max.
LM4	0.5 N·m max.

Keep the rotational torque below the permissible value.

If the rotational torque is applied too much, the rack bushing will wear in a short time.



Permissible Radial Load

Stroke mm	LM2□50	LM22200	LM4□20	LM4□1 ¹ 50 ^{: N}
100	25	25 ^{*1}	120	60 ^{*1}
200	20	20 ^{*1}	90	40 ^{*1}
300	10	10 ^{*1}	70	30* ¹
400	10	10 ^{*1}	60	25 ^{*1}
500	7	7 ^{*1}	50	20 ^{*1}
600	-	-	40	15 ^{*1}
1000	-	-	15	*2

● Either **F** (vertical to the mounting foot surface) or **B** (horizontal to the mounting foot surface) indicating the rack moving direction is entered where the box □ is located within the product name.

*1 The value is the operation speed up to 90 mm/s. When operating at a speed exceeding 90 mm/s, do not apply a radial load to the rack by providing a guide, etc..

*2 Do not apply a radial load to the rack by providing a guide, etc. since the rack is damaged.



Radial Load

Dimensions (Unit: mm)

LM2 B Type

◇Frame Size 60 mm High-Speed Type

Stroke mm	Product Name		L1	L2	Mass (Rack Mass Included)	Rack Mass kg	2D CAD
	AC Power Supply Input	DC Power Supply Input			kg	ng	
100	LM2B500AZAC-1	LM2B200AZAK-1	229.4		1.9	0.5	D7818
200	LM2B500AZAC-2	LM2B200AZAK-2	330.0		2.0	0.6	D7819
300	LM2B500AZAC-3	LM2B200AZAK-3	430.4		2.2	0.8	D7820
400	LM2B500AZAC-4	LM2B200AZAK-4	531.0	100	2.4	1.0	D7821
500	LM2B500AZAC-5	LM2B200AZAK-5	631.5	132	2.6	1.2	D7822
600	LM2B500AZAC-6	-	731.4		2.8	1.4	D7823
700	LM2B500AZAC-7	-	829.5		3.0	1.6	D7824
800	LM2B500AZAC-8	-	930.4		3.2	1.8	D7825

◇Frame Size 60 mm High-Speed Type with Electromagnetic Brake

Product Name Stroke Mass (Rack Mass Included) Rack Mass L2 2D CAD L1 mm kg kg AC Power Supply Input DC Power Supply Input LM2B500AZMC-1 LM2B200AZMK-1 2.2 0.5 D7826 100 229.4 LM2B500AZMC-2 LM2B200AZMK-2 200 330.0 2.3 0.6 D7827 300 LM2B500AZMC-3 LM2B200AZMK-3 430.4 2.5 0.8 D7828 LM2B500AZMC-4 LM2B200AZMK-4 400 531.0 2.7 1.0 D7829 178 500 LM2B500AZMC-5 LM2B200AZMK-5 631.5 2.9 1.2 D7830 LM2B500AZMC-6 600 731.4 3.1 1.4 D7831 700 LM2B500AZMC-7 829.5 3.3 1.6 D7832 LM2B500AZMC-8 930.4 800 3.5 1.8 D7833



2D & 3D CAD

2D & 3D CAD

LM2 F Type

\bigcirc Frame Size 60 mm High-Speed Type

2D & 3D CAD

2D & 3D CAD

Stroke mm	Product Name		L1	L2	Mass (Rack Mass Included)	Rack Mass	2D CAD
	AC Power Supply Input	DC Power Supply Input			kg	kg	
100	LM2F500AZAC-1	LM2F200AZAK-1	229.4		1.9	0.5	D7786
200	LM2F500AZAC-2	LM2F200AZAK-2	330.0		2.0	0.6	D7787
300	LM2F500AZAC-3	LM2F200AZAK-3	430.4		2.2	0.8	D7788
400	LM2F500AZAC-4	LM2F200AZAK-4	531.0	132	2.4	1.0	D7789
500	LM2F500AZAC-5	LM2F200AZAK-5	631.5	132	2.6	1.2	D7790
600	LM2F500AZAC-6	-	731.4		2.8	1.4	D7791
700	LM2F500AZAC-7	-	829.5		3.0	1.6	D7792
800	LM2F500AZAC-8	-	930.4		3.2	1.8	D7793

\Diamond Frame Size 60 mm High-Speed Type with Electromagnetic Brake

Stroke mm	Product Name		L1	L2	Mass (Rack Mass Included)	Rack Mass kg	2D CAD
	AC Power Supply Input	DC Power Supply Input			kg	r.y	
100	LM2F500AZMC-1	LM2F200AZMK-1	229.4		2.2	0.5	D7794
200	LM2F500AZMC-2	LM2F200AZMK-2	330.0]	2.3	0.6	D7795
300	LM2F500AZMC-3	LM2F200AZMK-3	430.4]	2.5	0.8	D7796
400	LM2F500AZMC-4	LM2F200AZMK-4	531.0	170	2.7	1.0	D7797
500	LM2F500AZMC-5	LM2F200AZMK-5	631.5	178	2.9	1.2	D7798
600	LM2F500AZMC-6	-	731.4]	3.1	1.4	D7799
700	LM2F500AZMC-7	-	829.5]	3.3	1.6	D7800
800	LM2F500AZMC-8	-	930.4]	3.5	1.8	D7801



The shaded areas are moving parts.

LM2 B Type

\bigcirc Frame Size 60 mm Large Transportable Mass Type

2D & 3D CAD

1	Stroke mm	Product Name		L1	L2	Mass (Rack Mass Included) kg	Rack Mass kg	2D CAD
		AC Power Supply Input	DC Power Supply Input			NY	ĸġ	
	100	LM2B90AZAC-1	LM2B50AZAK-1	229.4		2.1	0.5	D7802
	200	LM2B90AZAC-2	LM2B50AZAK-2	330.0		2.2	0.6	D7803
	300	LM2B90AZAC-3	LM2B50AZAK-3	430.4]	2.4	0.8	D7804
	400	LM2B90AZAC-4	LM2B50AZAK-4	531.0	170 5	2.6	1.0	D7805
	500	LM2B90AZAC-5	LM2B50AZAK-5	631.5	170.5	2.8	1.2	D7806
	600	LM2B90AZAC-6	-	731.4]	3.0	1.4	D7807
	700	LM2B90AZAC-7	-	829.5]	3.2	1.6	D7808
_	800	LM2B90AZAC-8	-	930.4		3.4	1.8	D7809

2D & 3D CAD

·								
Stroke	Product Name		L1	L2	Mass (Rack Mass Included)	Rack Mass	2D CAD	
mm	AC Power Supply Input	DC Power Supply Input			kg	kg		
100	LM2B90AZMC-1	LM2B50AZMK-1	229.4		2.5	0.5	D7810	
200	LM2B90AZMC-2	LM2B50AZMK-2	330.0		2.6	0.6	D7811	
300	LM2B90AZMC-3	LM2B50AZMK-3	430.4		2.8	0.8	D7812	
400	LM2B90AZMC-4	LM2B50AZMK-4	531.0	010.5	3.0	1.0	D7813	
500	LM2B90AZMC-5	LM2B50AZMK-5	631.5	216.5	3.2	1.2	D7814	
600	LM2B90AZMC-6	-	731.4	1	3.4	1.4	D7815	
700	LM2B90AZMC-7	•	829.5	1	3.6	1.6	D7816	
800	LM2B90AZMC-8	-	930.4	1	3.8	1.8	D7817	



LM2 F Type

\Diamond Frame Size 60 mm Large Transportable Mass Type

2D & 3D CAD

Stroke mm	Product Name		L1 L2	Mass (Rack Mass Included) kg	Rack Mass	2D CAD	
	AC Power Supply Input	DC Power Supply Input		229.4 330.0 430.4 531.0 631.5 731.4 829.5	Ng	kg	
100	LM2F90AZAC-1	LM2F50AZAK-1	229.4		2.1	0.5	D7770
200	LM2F90AZAC-2	LM2F50AZAK-2	330.0		2.2	0.6	D7771
300	LM2F90AZAC-3	LM2F50AZAK-3	430.4		2.4	0.8	D7772
400	LM2F90AZAC-4	LM2F50AZAK-4	531.0	170 5	2.6	1.0	D7773
500	LM2F90AZAC-5	LM2F50AZAK-5	631.5	170.5	2.8	1.2	D7774
600	LM2F90AZAC-6	-	731.4		3.0	1.4	D7775
700	LM2F90AZAC-7	-	829.5		3.2	1.6	D7776
800	LM2F90AZAC-8	-	930.4		3.4	1.8	D7777

	Transportable Mass Type	with Electromagnetic Brake
VFIAILIE SIZE OU IIIIII Large	mansportable mass type	with Electromagnetic brake

2D & 3D CAD

•	•				<u> </u>		
Stroke	Product Name		L1	L1 L2	Mass (Rack Mass Included)	Rack Mass kg	2D CAD
mm	AC Power Supply Input	DC Power Supply Input			kg	ĸġ	
100	LM2F90AZMC-1	LM2F50AZMK-1	229.4		2.5	0.5	D7778
200	LM2F90AZMC-2	LM2F50AZMK-2	330.0]	2.6	0.6	D7779
300	LM2F90AZMC-3	LM2F50AZMK-3	430.4]	2.8	0.8	D7780
400	LM2F90AZMC-4	LM2F50AZMK-4	531.0	0105	3.0	1.0	D7781
500	LM2F90AZMC-5	LM2F50AZMK-5	631.5	216.5	3.2	1.2	D7782
600	LM2F90AZMC-6	-	731.4]	3.4	1.4	D7783
700	LM2F90AZMC-7	-	829.5]	3.6	1.6	D7784
800	LM2F90AZMC-8	-	930.4]	3.8	1.8	D7785



The shaded areas are moving parts.

LM4 B Type

◇Frame Size 80 mm

2D & 3D CAD

Stroke mm	Produ	uct Name	L1 L2		Mass (Ra	ick Mass Included) kg	Rack Mass kg	2D CAD
	AC Power Supply Input	DC Power Supply Input			High-Speed Type	Large Transportable Mass Type	ĸy	
100	LM4B AZAC-1	LM4B AZAK-1	243.5		2.8	2.9	0.7	D7844
200	LM4B AZAC-2	LM4B AZAK-2	341.6		3.1	3.2	1.0	D7845
300	LM4B AZAC-3	LM4B AZAK-3	443.7		3.4	3.5	1.3	D7846
400	LM4B AZAC-4	LM4B AZAK-4	541.9		3.6	3.7	1.5	D7847
500	LM4B AZAC-5	LM4B AZAK-5	640.1	177.7	3.9	4.0	1.8	D7848
600	LM4B AZAC-6	LM4B AZAK-6	742.2	111.1	4.2	4.3	2.1	D7849
700	LM4B AZAC-7	-	840.4		4.5	4.6	2.4	D7850
800	LM4B AZAC-8	-	942.5		4.8	4.9	2.7	D7851
900	LM4B AZAC-9	-	1040.7]	5.1	5.2	3.0	D7852
1000	LM4B AZAC-10	LM4B AZAK-10	1142.8		5.4	5.5	3.3	D7853

\bigcirc Frame Size 80mm with Electromagnetic Brake

2D & 3D CAD

Stroke	Product Name		L1 L2		Mass (Ra	Rack Mass	2D CAD	
mm	AC Power Supply Input	DC Power Supply Input]		High-Speed Type	Large Transportable Mass Type	kg	
100	LM4B AZMC-1	LM4B AZMK-1	243.5		3.2	3.3	0.7	D7864
200	LM4B AZMC-2	LM4B AZMK-2	341.6		3.5	3.6	1.0	D7865
300	LM4B AZMC-3	LM4B AZMK-3	443.7		3.8	3.9	1.3	D7866
400	LM4B AZMC-4	LM4B AZMK-4	541.9		4.0	4.1	1.5	D7867
500	LM4B AZMC-5	LM4B AZMK-5	640.1	223.7	4.3	4.4	1.8	D7868
600	LM4B_AZMC-6	LM4B AZMK-6	742.2	223.1	4.6	4.7	2.1	D7869
700	LM4B AZMC-7	-	840.4		4.9	5.0	2.4	D7870
800	LM4B_AZMC-8	-	942.5]	5.2	5.3	2.7	D7871
900	LM4B AZMC-9	-	1040.7]	5.5	5.6	3.0	D7872
1000	LM4B AZMC-10	LM4B AZMK-10	1142.8		5.8	5.9	3.3	D7873
	LM4B AZMC-10	LM4B AZMK-10			5.8	5.9		



igodot A number indicating the rack maximum speed is entered where the box \Box is located within the product name.

40 (40 mm/s) or 500 (500 mm/s) for the AC power input and 20 (20 mm/s) or 150 (150 mm/s) for the DC power input is entered, respectively. The shaded areas are moving parts.

LM4 F Type

\Diamond Frame Size 80 mm

2D & 3D CAD

2D & 3D CAD

	Stroke mm	Product Name		L1	L2	Mass	(Rack Mass Included) kg	Rack Mass	2D CAD
		AC Power Supply Input	DC Power Supply Input			High-Speed Type	Large Transportable Mass Type	ĸy	
	100	LM4F_AZAC-1	LM4F_AZAK-1	243.5		2.8	2.9	0.7	D7834
	200	LM4F AZAC-2	LM4F□AZAK-2	341.6		3.1	3.2	1.0	D7835
	300	LM4F_AZAC-3	LM4F_AZAK-3	443.7		3.4	3.5	1.3	D7836
	400	LM4F□AZAC-4	LM4F□AZAK-4	541.9		3.6	3.7	1.5	D7837
	500	LM4F AZAC-5	LM4F AZAK-5	640.1	177.7	3.9	4.0	1.8	D7838
	600	LM4F AZAC-6	LM4F□AZAK-6	742.2	1//./	4.2	4.3	2.1	D7839
	700	LM4F AZAC-7	-	840.4		4.5	4.6	2.4	D7840
	800	LM4F AZAC-8	-	942.5		4.8	4.9	2.7	D7841
	900	LM4F AZAC-9	-	1040.7		5.1	5.2	3.0	D7842
_	1000	LM4F AZAC-10	LM4F AZAK-10	1142.8		5.4	5.5	3.3	D7843

\Diamond Frame Size 80 mm with Electromagnetic Brake

Stroke	Product Name		L1	L1 L2	Mass (Ra	Rack Mass	2D CAD	
mm	AC Power Supply Input	DC Power Supply Input]		High-Speed Type	Large Transportable Mass Type	kg	
100	LM4F AZMC-1	LM4F AZMK-1	243.5		3.2	3.3	0.7	D7854
200	LM4F AZMC-2	LM4F AZMK-2	341.6		3.5	3.6	1.0	D7855
300	LM4F AZMC-3	LM4F AZMK-3	443.7		3.8	3.9	1.3	D7856
400	LM4F AZMC-4	LM4F AZMK-4	541.9	641.9	4.0	4.1	1.5	D7857
500	LM4F AZMC-5	LM4F AZMK-5	640.1	223.7	4.3	4.4	1.8	D7858
600	LM4F AZMC-6	LM4F AZMK-6	742.2	223.1	4.6	4.7	2.1	D7859
700	LM4F AZMC-7	-	840.4		4.9	5.0	2.4	D7860
800	LM4F AZMC-8	-	942.5]	5.2	5.3	2.7	D7861
900	LM4F AZMC-9	-	1040.7	1	5.5	5.6	3.0	D7862
1000	LM4F AZMC-10	LM4F AZMK-10	1142.8		5.8	5.9	3.3	D7863



 \blacksquare A number indicating the rack maximum speed is entered where the box \square is located within the product name.

Peripheral Equipment

Photomicrosensor Sets

A photomicrosensor set, which consists of a photomicrosensor (with flexible cable), sensor mounting bracket, shielding plate and installation screw, is provided to facilitate easy return-to-home operation.

All parts needed for return-to- home operation are included in the set, so you will spend less time designing, fabricating or procuring parts in connection with sensor installation.

Features

Compact

This is a compact sensor that takes into consideration the installation space. It is easy to detect the rack position.

Two Output Signals are Available

By installing a sensor on both sides of the rack, it is possible to detect two signals at the both moving ends or the signals at the moving end and the intermediate stop position, separately.

Product Line

Product Name	Applicable Product	List Price
PARP-PS2B	LM2	
PARP-PS4B	LM4	

The following items are included with the product. Photomicrosensors* (2 pieces), Shielding Plates (4 pieces), Sensor Mounting Bracket (1 piece), Photomicrosensor Installation Screws (4 pieces), Operating Manual * With Flexible Cable (3 m)

Specifications

Product Name	EE-SX951-R (OMRON)
Power Supply Voltage	5 to 24 VDC \pm 10%, Ripple (Peak to Peak) 10% max.
Consumption Current	15 mA or less
Control Output	NPN Open-Collector Output, 5 to 24 VDC, 50 mA or less Residual Voltage: 0.7 VDC or less (At load current of 50 mA) : 0.4 VDC or less (At load current of 5 mA)
Indicator LED	Detection Indication (Red)
Logic	Normally Open/Normally Closed (Possible to switch by connection)



Sensor Mounting Bracket

Photomicrosensor

Photomicrosensor

Installing Screw (M3)

 $\ensuremath{\boldsymbol{\ast}}\xspace$ Use the screws included with the rack case.

Dimensions (Unit: mm) PARP-PS2B Photomicrosensor 50



The dimensions with photomicrosensor set attached to L Series are available. Refer to the Oriental Motor website.

PARP-PS4B Photomicrosensor 5



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Rack Cover (For Photomicrosensor)

It is a simple cover that protects the rack from impact and particles adhesion.

It also prevents grease from adhering to human body, equipment and so on. Use it together with photomicrosensor set sold separately.

Product Name	Applicable Product	Applicable Stroke (mm)	List Price
2LSC-P02	LM2	100, 200	
2LSC-P04	LMZ	300, 400	
4LSC-P02	LM4	100, 200	
4LSC-P04		300, 400	

